

Shri Shankaracharya Technical Campus, Bhilai

(An Autonomous Institute Affiliated to CSVTU Bhilai)

SCHEME OF TEACHING AND EXAMINATION B. Tech. Seventh Semester- ELECTRICAL AND ELECTRONICS ENGINEERING

Sl.				Course	P	erio per	d	Sc Exa	heme amina	of tion	Τ	C
No.	Board of Studies	Courses (Subject)	Category	Code	-	_	-	Th	eorv/	Lab	ota ark	red
	(BOS)				L	Т	P	ESE	ĊT	TA	s I	it
1.	Electrical and Electronics	Power System Protection	PEC	EEE103701	2	1	-	100	20	30	150	3
2.	Electrical and Electronics	Electrical Drives	OEC	EEE103702	2	1	-	100	20	30	150	3
3.	Electrical and Electronics	Computer Aided Power System	OEC	EEE103703	3	-	-	100	20	30	150	3
4.	Electrical and Electronics	Professional Elective-II (Refer Table-1)	HSMC	EEE103722	3	-	-	100	20	30	150	3
5.	Electrical and Electronics	Open Elective-1 (Refer Table-2)	HSMC	EEE103732	3	-	-	100	20	30	150	3
6.	Electrical and Electronics	Power System Protection Lab	PEC	EEE103791	-	-	2	25	-	25	50	1
7.	Electrical and Electronics	Electrical Drives Lab	PCC	EEE103792	-	-	2	25	-	25	50	1
8.	Electrical and Electronics	Capstone Project Phase I	PSI	EEE103793	-	-	4	50	-	50	100	2
9	Electrical and Electronics	Internship assessment/Industrial training	PSI	EEE103794	-	-	2		-	25	25	1
10.	Electrical and Electronics	Universal Human Values and Professional Ethics	NC	EEE103795	-	-	-	-	-	25	25	-
	Total						8	600	100	300	1000	20

L: Lecture, T: Tutorial, P: Practical, ESE: End Semester Exam CT: Class test TA: Teacher's assessment

	Table IV : Professional Elective - III							
Sl. No.	Board of Studies (BOS)	Course(Subject)	Course Code					
1.	Electrical & Electronics Engineering	Switched Mode Power Converter	EEE103721					
2.	Electrical & Electronics Engineering	Power Apparatus System	EEE103722					
3.	Electrical & Electronics Engineering	Flexible AC Transmission Systems	EEE103723					
4.	Electrical & Electronics Engineering	Internet of Things	EEE103724					
5.	Electrical & Electronics Engineering	Advance Control Theory	EEE103725					

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B.	Tech.	(Electrical	and El	ectronics	Engine	ering)	Seventh	Semester
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	Table V : Open Elective - II							
Sl. No.	Board of Studies (BOS)	Course(Subject)	Course Code	Link				
1.	Electrical & Electronics Engineering	Soft Computing Techniques	EEE100741					
2.	Electrical & Electronics Engineering	Introduction to Machine Learning	EEE100742	https://onlinecourses.nptel.ac.in/noc23_ ee87/preview				

Note:

(a) Abbreviations used : L-Lecture, T-Tutorial, P-Practical, ESE- End Semester Exam, CT- Class Test, TA- Teacher's Assessment

(b) 1/4th of total strength of students subject to minimum of 20 students is required to offer an elective in the department in a particular academic session.

(c) Choice of elective course once made for an examination cannot be changed in future examinations.

 $(d) \quad \mbox{The duration of end semester examination of all theory papers will be of three hours.}$

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B.TECH. (DEPARTMENT OF

ELECTRICAL & ELECTRONICS

ENGINEERING)

SEVENTH SEMESTER

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Subject Code EEE103701	Power System Protection	L = 2	T = 1	P = 0	Credits = 3
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes				
The objective of the course to:	Students will be able to:				
 To understand the principle of protective schemes and various faults in the Power System Scenario. To study the various types of the circuit breakers, the arc quenching phenomena and the protection against over voltages. Teach students the protection systems used for electric machines, transformers, bus bars. 	 understand the principle of protective emes and various faults in the Power tem Scenario. study the various types of the circuit akers, the arc quenching phenomena and protection against over voltages. ch students the protection systems used for tric machines, transformers, bus bars. CO1 Design the relevant p systems for the main ele a power system CO2 Analyze with over differential, and ratio p devices and their applica coordinated protection so CO3 Do the stability proble clearing of faults to these problems. 				
UNIT 1		CO1			
Protective relays : Introduction to protective Relay, importance of protective relaying, primary and backup protection, desirable qualities of protective relaying, protective current transformer and voltage transformer, basic connection of trip circuit, principle, construction, working& torque equation of instantaneous overcurrent relay, IDMT relay, differential relay, directional relay, generalized torque expression, impedance relay, reactance relay, mho relay.					
UNIT 2		CO1,			
a) Generator protection: Fault on generators, Differential protection of stator, inter turn fault protection, protection against unbalance loading, protection of rotor against ground fault, protection against field failure, protection against failure of prime mover, field suppression in alternators.					
b) Transformer protection: Difficulties in differential protection, mode of C.T. connection for differential protection of three phase transformer, protection against magnetizing inrush current, core balance earth leakage protection.					

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UNIT 3	CO3
 a) Transmission line protection: Over current protection of lines, three step distance protection, effect of power swings on distance relay, Directional comparison carrier current protection, phase comparison carrier current protection, carrier aided distance protection. b) Feeder protection: protection of ring main feeder, protection of parallel feeders. c) Bus bar protection: Differential protection, frame leakage protection. 	10Hrs
UNIT 4	CO3
Static relay: Amplitude & phase comparators, duality between amplitude & phase comparators, circulating current amplitude comparators, coincidence technique in phase comparator, spike and block phase comparator, integrating phase comparator, Hall effect sine phase comparator, Design of directional relay, reactance relay, mho relay, impedance relay, quadrilateral characteristics relay using cosine phase comparator and amplitude comparator.	10 Hrs
UNIT 5	CO3
Circuit Breakers: Initiation of Arc, Arc interruption theories, current chopping, Recovery voltage, Factor affecting recovery voltage, Restriking voltage, rate of rise of restriking voltage, Breaking of capacitive current, Resistance switching, Circuit Breaker rating, Circuit Breaker testing, Minimum oil circuit breaker, Air Blast circuit Breaker, SF-6 Circuit Breaker.	8 Hrs

	S .			Edition	
ľ	No.	Title	Authors		Publisher
	1	Power System Protection and Switchgear	Badri Ram, Vishwakarma D N.	2005	Tata McGraw Hill Publishing House Limited, New
	2	Fundamentals of Power System Protection	Paithankar Y. G., Bhide S. R.	2 nd	Prentice Hall of India Limited, New Delhi

Text Books:

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Reference Books:

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S.			Edition	
No.	Title	Authors		Publisher
1	Electrical Power Systems	Wadhwa, C.L.	6 th	New Age International Publishers Limited
2	A Text Book on Power Systems Engineering	Soni, M.L., Gupta, P.V., Bhatnagar, U.S. and Chakrabarti, A	2008	Dhanpat Rai & Sons Company Limited, New Delhi
3	Power system Protection And Switchgear	Oza, Nair, Mehta and Makwana		

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Subject Code EEE103702	Electrical Drives	L = 2	T = 1	P = 0	Credits = 3
Fyaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

	Course Objectives		Course Outcomes		
The o	bjective of the course to:	On	successful complet	ion of the course,	
1.	Describe the structure of Electr	ric Drive the	student		
	systems and their role in variou	is applications. wi	ll be able to:		
2. 3. 4. 5. 6.	Describe the operation of dc m satisfy four-quadrant operation mechanical load requirements. Describe the operation of induc in steady state. Describe speed control of induc drives in an energy efficient ma power electronics. Describe synchronous motor da Describe operation of tractions	otor drives to to meet CC ction machines CC ction motor anner using CC rive operation. CC Drives.	 1 Electric drive different mode o 2 Performance and on the basis cooling. 3 Speed control of using Power Electron of the substant of the basis cooling. 4 Speed control machines using I devices. 5 Operation of the basis of the basis control of the basis cooling. 	systems for f operations. I ratings of drive of heating and of DC machines ctronics devices. of DC and AC Power Electronics	
TINIT	D 1		5 Operation of trac		
 UNIT 1 Electric Drives: Basic concept of electric drives its advantages and types, choice of electric drives, Fundamental equations, speed torque conversions and multi quadrant operation, drive parameters, component of load torque, nature and classification of load torques, calculation of time and energy loss in transient operation, steady state stability and load equalization. 			con choice 12 Hrs multi e and nsient		
UNIT 2 Control and Rating of Electric Drives : Modes of operation of electric drives, Closed loop control of drives, closed loop control of multi-motor drives, Selection of motor power rating-Heating and Cooling of motors, Selection of motor power rating under different loading conditions, Continuous ,Short and Intermittent periodic duty.			cO2 lrives, ection power nittent		
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UNIT 3	CO3
DC Drives: Review of dc motors and their performance, Braking: Regenerative braking, Dynamic braking, Plugging. Speed control, Controlled Rectifier fed dc drives: single phase and three phase half controlled and fully controlled, Multi quadrant operation of dc drives, Chopper Controlled dc drives	IUHTS
UNIT 4	CO4
Induction and Synchronous Motor Drives: Review of conventional method of starting, and Speed control, Braking: Regenerative braking, Dynamic braking, Plugging. Speed control by stator voltage control, supply frequency control, Voltage source inverter (VSI) and current source inverter (CSI) fed three-phase induction motor drives, Static rotor resistance control induction motor drive, Slip power recovery drives. Synchronous motor drives: Speed control of synchronous motor using voltage and current source inverters, Self-controlled synchronous motor drives.	10 Hrs
UNIT 5	CO5 8Hrs
Traction Drives : Electric Traction system, Nature of traction load, calculation of Traction drive rating and energy consumption, Important feature of traction drives, Motors employed in traction, Conventional method for AC and DC traction drives control, Semiconductor converter-controlled drives employing DC motors, AC motors for 25 KV AC traction.	

S. No.	Title	Authors	Edition	Publisher
1)	Fundamentals of electrical drives	G K Dubey	2nd	Narosa Pb
2)	Electric Drives	Vedam Subramanyam	2nd	TMHP bs

Text Books:

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S. No.	Title	Authors	Edition	Publisher
1)	Electric Motor Drives	R. Krishnan	1st edition 2001	PHI Pb
2)	Modern Power Electronics and AC Drives	B K Bose	12 October 2001	Pearson Education

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Subject Code EEE103703	Computer Aided power System	L = 3	T = 0	P = 0	Credits = 3
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes	
The objective of the course to:	On successful completion of the course,	
 Modeling issues and analysis methods for the power flow, short circuit, contingency and stability analyses, required to be carried out for the power systems. Necessary details of numerical techniques to solve nonlinear algebraic as well as differential equations will also be included. Different types of stability phenomena have been observed hi the power systems, which need to be critically analyzed, utilizing appropriate dynamic model of the system. 	the student will be able to: CO1: Develop proper mathematical models for analysis of a selected problem like load flow study or fault analysis. CO2: Student able to analysis of different type fault in a power system. CO3: Student able to understands different load flow techniques. CO4: Student able to understand stability analysis of power system. CO5: Student able to understand the power system concepts of contingency analysis.	
UNIT 1	CO1	
Network equations: Network equations, graph theory. Bus admittance matrix by step by step method, primitive network, bus incidence matrix, formation of Y_{bus} by singular transformation, bus impedance matrix by inversion of Y_{bus} algorithm for bus impedance matrix, addition of a branch, addition of link, modification of Z_{bus} by changes in primitive network. Concept of using these matrices for load flow study and fault study.		
UNIT 2 Fault Analysis: Fault Analysis, [ZBUS] Building a Symmetrical and Unsymmetrical Short-Circuit Analysis of Large Power Systems, Phase due to transformers.	lgorithm, sequence matrices, e Shift in sequence quantities	

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UNIT 3 Load Flow Study: Introduction, power system equations, solution technique ie Gauss Seidel, Newton Raphson and fast decoupled load flow.	CO3 10Hrs
UNIT 4	CO4
Transient Stability Studies: Introduction, swing equation, machine equations, power system equations, solution techniques, example of transient stability calculations, avaitant and governor control system description of transient stability.	12 Hrs
program.	
UNIT 5	CO5
Security Analysis: Basic Concepts, Power System Security, Factors affecting Security Static Security Analysis at Control Centers, Contingency Analysis, Contingency Selection, Contingency Analysis Using Network Sensitivity Method and AC Power Flow Method.	7Hrs

S.			Edition	
No.	Title	Authors		Publisher
1	Dower System Analysis	U Sadat	2000	McGraw Hill Co.
1	Fower System Analysis	п. Sauai	2000	Ltd
2	Computer methods in Power System Analysis	G. W. Stagg and A. H. El- Abiad	1968	Mc -Graw Hill Kogakusha Ltd

Reference Books:

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S.			Edition	
No.	Title	Authors		Publisher
1.	Computer Aided Power System Analysis & Control	A.K. Mahaianabis, D.P. Kothari, S.I. Ahson	1988	McGraw Hill, New Delhi
2	Electric Energy System Theory: An Introduction	O.I. Elgard	1982	McGraw Hill, New York

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Subject Code EEE103791	Power System Protection Lab	L =0	T = 0	P = 2	Credits = 1
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	25		25	50	

List of Experiments

List of Experiments (At least ten experiments are to be performed by each student)

1. To study Over current Relay static type & draw characteristics.

2. To study under voltage relay Electromechanical type & draw characteristics.

3. To study over voltage relay Electromechanical type & draw characteristics.

4. To study IDMT Over current relay Electromechanical Type & draw current verses time characteristics.

5. To study IDMT earth fault relay electromechanical type draw current verses time characteristics.

6. To study operating characteristics of percentage-biased differential relays tp plot the characteristics of percentage biased differential relay for 30%, 40%, & 20%.

7. To determine the characteristics of instantaneous relays.

8. To study Bucholz Relays.

9. To study Solid State O.C.R.

10. To study Merz Price Protection of transformer (Simulation Model).

11. To study Static type negative sequence relay.

12. To study the time-grading protection of feeder [simulation Model].

13. To study the current-grading protection of feeder [simulation Model].

14. To study the time-current grading protection of feeder [simulation Model].

15. To study the simulation model for short, medium, & long transmission line.

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Subject Code EEE103792	Electric Drives Laboratory	L =0	T = 0	P = 2	Credits = 1
Fyaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	25		25	50	

List of Experiments

List of experiments: (Minimum 10 experiments to be performed)

- 1. To study the heating time constant for a Continuous Duty Motor
- 2. To Study the heating time constant of a Short time Duty Motor
- 3. To Study the cooling time constant of a Short time Duty Motor
- 4. To Study the heating time constant of a Short Time Duty Motor
- 5. To Study the cooling time constant for an Intermittent Duty Motor
- 6. Performance and speed control of D.C drive using 3-phase full converter
- 7. Performance and operation of a four quadrant chopper on D.C drive
- 8. Study and performance of electrical Dynamic braking and Plugging of D.C shunt motor
- 9. Study of V/F control operation of 3-φ Induction motor

10. Simulation of PWM VSI/CSI fed 3-φ Induction motor control using MATLAB/PSPICE/PSIM software

11. Study of solid state stator voltage control of $3-\phi$ Induction motor (using AC voltage regulator)

- 12. Performance and speed control of 3- Induction motor using 3- voltage source inverter
- 13. To study frequency control Synchronous motor drive
- 14. Study of AC motors for 25KV Ac traction
- 15. Study of Resistance wielding and Arc welding

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Subject Code EEE103721	Switched Mode Power Converter	L = 3	T = 0	P = 0	Credits = 3
Fyaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes	
Course ObjectivesThe objective of the course to:1. To understand various modes of operation of switched mode power converters2. To analyze control aspects of switched mode power converters3. To design various switched mode power converter and its components	Course Outcomes On successful completion of the course, the student will be able to: CO1: Model and develop switching power converters topologies. CO2: Describe the role of switch mode power converters in various	ne ng ch us
	applications. CO3: Design magnetic component for DC-DC converters	its
UNIT 1 Switching devices and control of switched mode po Power semiconductor devices for SMPS- static an power loss evaluation, turn-on and turn-off char Modeling and control of SMPS, duty cycle and currer	d switching characteristics, racteristics, PWM control, nt model control.	5
UNIT 2 Non-Isolated switched mode power converters: Ne buck, boost, buck-boost, Cuk, Sepic; continuou discontinuous conduction mode analysis; non-ideal power converters.	on-isolated dc-dc converter- us conduction mode and ities in the switched mode	CO2
UNIT 3 Isolated switched mode power converters: Isolated forward, push-pull, half bridge and full bridge topolo high frequency isolation.	dc-dc converters- fly back, gies; transformer design for	
UNIT 4 Resonant Converters: Introduction, resonant switch operation and analysis, resonant switch ZVS converte analysis, Series resonant inverter, series resonant	ZCS converter, principle of or, principle of operation and DC-DC converter, parallelCO3 Hrs	12

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resonant DC-DC converter, series- parallel resonant DC-DC converter, resonant converters comparison.	
UNIT 5	CO2,CO3
Design considerations: Selection of output filter capacitor, Selection of energy storage inductor, Design of High Frequency Inductor and High frequency Transformer, Selection of switches, Snubber circuit design, Design of driver circuits.	9Hrs

Text Books:

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S. No.	Title	Authors	Publisher
1	Switched Mode Power Supplies	H. W. Whittington, B. W. Flynn and D.	Universities Press
2	Power Electronics Converters, Application and Design	Mohan N. Undeland . T & Robbins W.,	Wiley, Third edition,
3	Design of magnetic components for switched Mode Power Converters	Umanand L., Bhat S.R.	newage publishers

Reference Books:

S. No.	Title	Authors	Publisher
1	Elements of Power Electronics	Krein P.T.	Oxford University Press

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Subject Code EEE103722	Power Apparatus System	L = 3	T = 0	P = 0	Credits = 3
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes
The objective of the course to:	On successful completion of the course,
1. Acquire knowledge of overhead line insulator,	the student
string efficiency and sag and tension calculation	will be able to:
of transmission line.	CO1: Understand the concepts of
2. Describe different types of Distribution system.	microprocessors, their principles and
system	practices.
4. Explain insulation coordination and surge	CO2: Write efficient programs in
protection.	assembly language of the 8086 family
5. Correlate basic concept of reliability with	of microprocessors.
Reliability of transmission and Distribution	CO3: Organize a modern computer
System.	system and be able to relate it to real
	examples.
	CO4: Develop the programs in
	assembly language for 80286, 80386
	and MIPS processors in
	CO5: real and protected modes.
	Implement embedded applications
	using ATOM processor.
UNIT 1	C01
Mechanical Design of Transmission Lines:	6 Hrs
Types of Insulator, Conductors, Towers, Span, Conductors, Span	ductor Configuration, Spacing,
Clearance, Sag and Tension Calculation, Potential	l distribution over a string of
suspension insulators, string efficiency, methods	for equalizing the potential,
Selection of Conductor Size, Number of Circuit, G	round Wire, Surge Impedance
Loading.	
	C01
UNIT 2	6 Hrs
Distribution System: Types of Distribution System	n, Various types of AC & DC
Distributors, Voltage Drop Calculation, Selection of	f Distribution Voltage, Size of
Conductor, Kelvin's Law.	

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	1
UNIT 3	CO3
Power System Grounding: Different Methods of grounding : Neutral Grounding,	8Hrs
Solid Grounding, Resistance Grounding, Reactance Grounding, Arc Suppression	
Coil Grounding, ZigZag Transformer Grounding, Effect of Grounding on System	
Over Voltages. Merits & Demerits of Various Grounding Systems.	
UNIT 4	CO3
Surge Protection & Insulation coordination: External & Internal Overvoltage	8 Hrs
Mechanism of Lightening Discharge, Wave Shapes of Stroke Current, Line Design	
on Direct Stroke Over Voltage Protection, Earth Wire, Rod Gap, TRF, Expulsion	
Tube, Surge Diverter Selection of BIL, International Recommendation, Selection	
of Arrestor Rating, Coordination of Protector Devices With Apparatus Insulation.	
UNIT 5	CO5
Reliability of Transmission and distribution System: Definitions : Outage , Bath	8Hrs
Tub Curve , Causes of Failures, Two State Model, Failure & Repair Rate,	
Probability Density Function, Reliability of Series / Parallel System, Reliability	
Planning, Preparation of Reliability Models. Numerical problems related to	
Reliability of Transmission and distribution system.	

Text Books:

S.			Edition	
No.	Title	Authors		Publisher
1	Power System Analysis & Design	B.R. Gupta G. Zaky	2005	S.Chand Publications
2	A Course in Electrical Power	Soni, Gupta and Batnagar	2013	Dhanpat Rai and Sons.

Reference Books:

S.			Edition	
No.	Title	Authors		Publisher
1	Flootrical Power System Design	M. V.	UK ed. edition (16	тмц
1.	Electrical Fower System Design	Deshpande	February 1985)	1 1/111

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Subject Code EEE10723	Flexible AC Transmission System	L = 3	T = 0	P = 0	Credits = 3
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes
The objective of the course to:	On successful completion of the
 To understand the fundamentals of FACTS Controllers, Importance of controllable parameters and types of FACTS controllers & their benefits To recall the objectives of Shunt and Series compensator. To explain ccontrol of STATCOM and SVC and their comparison And the regulation of STATCOM To analyze the functioning and control of GCSC, TSSC, TCSC and SSSC To analyze the functioning and control of combined Compensators(IPFC& UPFC 	course, the student will be able to: CO1: Choose proper controller for the specific application based on system requirements and Understand various systems thoroughly and their requirements. CO2: Interpret the control circuits of Shunt Controllers SVC & STATCOM for various functions viz. Transient stability Enhancement. CO3: Detect the Power and control circuits of Series Controllers GCSC, TSSC, TCSC,SSSC and Detect the Power and control circuits of combined Compensators(IPFC& UPFC)
UNIT 1	CO1
Facts Concepts	aission problems and passed
Overview of stability Power Flow in AC System	FACTS Concept and General
System Considerations . Definitions on FACTS	S. Basic types of FACTS
Controllers.	
UNIT 2	C01,
Static Shunt Compensators Concept of Static Shunt Compensators, varial compensators (TCR, TSC, FC-TCR, TSC-TCR) - operation, working, waveforms / characteristics. Switched converter type shunt compensator (SVC diagram, principle of operation, working, waveforr STATCOM, and its control scheme .Comparison betw	ble impedance type shunt circuit diagram, principle of C and STATCOM) - circuit ms / characteristics SVC and ween SVC and STATCOM

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UNIT 3	CO3
Static Series Compensators	8Hrs
Concept of series compensation, variable impedance type series compensators	
(GCSC, TSSC, TCSC, SSSC), Switching converter type series compensators -	
circuit diagram, principle of operation, working, waveforms/characteristics,	
control schemes for series compensators.	
UNIT 4	CO3
Combined Series-Series FACTS compensators and other special purpose of	8 Hrs
Interline power flow controller (IPFC) - objectives and need, principle of	
operation.	
Combined Series-Shunt FACTS compensators and other special purpose of	
Unified Power flow Controller (UPFC) - objectives and need, principle of	
operation .	
UNIT 5	CO2,CO3
Objectives of Static voltage and phase angle regulators, power flow control,	9Hrs
improvement of transient stability, power oscillation damping, thyristor-controlled	
voltage and phase angle regulators.	

Text Books:

S. No.	Title	Authors	Publisher
1	Understanding FACTS: Concepts and Technology of Flexible AC Transmission Systems	.G. Hingorani & L. Gyugyi	IEEE Press, 2000.
2	Reactive Power Control in Electric Systems	T.J.E Miller	John Wiley & Sons, 2003

ReferenceBooks:

S. No.	Title	Authors	Publisher
1	Thyristor-based FACTS controller for electrical transmission system, IEEE series on power Engineering	R. Mohan Mathur and Rajiv K. Varma	Wiley Interscience, 2002
2	FACTS Controllers and applications, course book	Dr Ashok S & K S Suresh Kumar	SUP, 2003.
3.	FACTS controllers in power transmission and distribution	Padiyar K. R	New Age Publishers, India, 2007.

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तरन्त्रम "

Subject Code EEE103724	Internet of Things	L = 3	T = 0	P = 0	Credits = 3
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes
The objective of the course to:	On successful completion of the course,
1. To prepare the students to understand the	the student
Internet of Things.	will be able to:
2. To make students understand the applications of IoT.	CO1: Understand the meaning of IOT
3. To make students understand the difference between IoT and WoT	CO2: Apply IoT in various applications in day to day life.
	CO3: Able to understand architecture of Internet of Things and characteristics
UNIT 1	CO1
IOT	4 Hrs
Tashnalagy drivers Dysiness drivers Trends and	implications Overview of
Governmence Privacy and Security Issues	implications, Overview of
Governance, I fivacy and Security issues.	
UNIT 2	CO2 5 Hrs
IOT PROTOCOLS	
Protocol Standardization for IoT – Efforts – M2M an	d WSN Protocols – SCADA
and RFID Protocols - Issues with IoT Standardization	n – Unified Data Standards –
Protocols – IEEE802.15.4–BACNet Protocol– Modbu	s – KNX – Zigbee– Network
layer – APS layer – Security.	
UNIT 3	CO3 12Hrs
IOT ARCHITECTURE	
101 Open source architecture (OIC)- OIC Architecture	e & Design principles- IoT
Devices and deproyment models- to rivity. An Open s	ource for stack - Overview-

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IoTivity stack architecture- Resource model and Abstraction.	
UNIT 4 WEB OF THINGS Web of Things versus Internet of Things – Two Pillars of the Web – Architecture Standardization for WoT– Platform Middleware for WoT – Unified Multitier WoT Architecture – WoT Portals and Business Intelligence.	CO1 CO2 8 Hrs
UNIT 5 IOT APPLICATIONS IoT applications for industry: Future Factory Concepts, Brownfield IoT, Smart Objects, Smart Applications. Study of existing IoT platforms /middleware, IoT- A, Hydra etc.	CO1 7Hrs

Text Books:

S. No.	Title	Authors	Edition	Publisher
1	The Internet of Things in the Cloud: A Middleware Perspective	Honbo Zhou,	2012	CRC Press
2	Architecting the Internet of Things	Dieter Uckelmann, Mark Harrison, Michahelles, Florian (Eds),	2011	Springer
3	Networks, Crowds, and Markets: Reasoning About a Highly Connected World	David Easley and Jon Kleinberg	2010	Cambridge University Press

Reference Books:

S. No.	. Title		Authors		Edition	Publisher
1	Internet (A Hands-o	of Things n-Approach)	Vijay Madisetti ArshdeepBahş	and ga	1 st Ed	VPT
Rethinking the Internet of Things: A Scalable Approach to Connecting EverythingFrancis		Francis da Cos	sta	1 st Ed 2013	Apress Publications	
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Subject Code EEE103725	Advance Control Theory	L = 3	T = 0	P = 0	Credits = 3
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes
The objective of the course to:	Students will be able to:
1. To provide a strong concept on the compensator design and on advanced control	CO4 Design compensators using classical techniques.
system analysis and design techniques	CO5 Analyze both linear and
2. To analyse the behaviour of discrete time systems and nonlinear control systems.	nonlinear system using state space methods.
	CO6 Design state feedback controller
	for a given system
	CO7 Explain the characteristics of
	nonlinear systems
	CO8 Analyze the stability of discrete
	and non-liner control system
UNIT 1	C01
 Types of controller- Feedforward-feedback-cascadedesign: Realization of compensators – lag, lead compensator using bode plot. Compensator design: Realization of compensators – of compensator using rootlocus. Design of P, PI and Nichols tuning method. 	-P, PI and PID. Compensator d and lag-lead -Design of lag, lead and lag-lead. Design PID controller using Ziegler-
UNIT 2	CO2
STATE SPACE ANALYSIS OF SYSTEMS : Introd equation of linear continuous time systems, matrix rep Phase variable and canonical forms of state representa and diagonal and Jordan canonical forms- solution of systems, forced system-state transition matrix-relation	Auction to state concept - state9 Hrsbresentation of state equations.ation-controllable, observable,of time invariant autonomousnship between state equations

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and transfer function.	
UNIT 3	CO3
State feedback controller design: Controllability & observability. State feed-back design via pole placement technique. Sampled data control system: Pulse Transfer function-Stability of sampled data system -Routh Hurwitz criterion and Jury's test. Introduction to state-space representation of sampled data systems.	10 Hrs
UNIT 4	CO4
Nonlinear systems: Introduction - characteristics of nonlinear systems. Types of nonlinearities. Analysis through harmonic linearisation - Determination of describing function of nonlinearities (relay, dead zone and saturation only) – application of describing function for stability analysis of autonomous system with single nonlinearity.	8 Hrs
UNIT 5	CO5
 Phase Plane Analysis: Concepts- Construction of phase trajectories for nonlinear systems and linear systems with static nonlinearities - Singular points - Classification of singular points. Definition of stability- asymptotic stability and instability Liapunov methods to stability of linear and nonlinear, continuous time systems. 	8Hrs

Text Books:

S. No.	Title	Author(s)	Publisher
1	Control System Engineering	Nagarath I. J. and Gopal M	5/e, New Age Publishers, 2007
2	Modern Control Engineering	Ogata K	5/e, Prentice Hall of India, 2010
3.	Nonlinear Automatic Control	Gibson J.E	Mc Graw Hill, 1963

Reference Books:

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1	Modern Control System Theory	Gopal M	2/e, New Age Publishers, 1984
2	Analysis and Synthesis of Sampled Data Systems	Kuo B.C	Prentice Hall Publications, 2012

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Subject Code EEE100741	Soft Computing Techniques	L = 3	T = 0	P = 0	Credits = 3
Evaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcomes	
The objective of the course to:	On successful completion	of the
 The main objective of the course is to familiarize students with the underlying principle of soft computing with its usage in various applications to solve real life problems. This course provides knowledge on electrical traction systems. 	 course, the student will be able to: CO1: Identify and desc computing techniques and their building intelligent machines. CO2: Describe Artificia Networks and Applications. CO3: Describe Fuzzy Syst Applications. CO4: Describe Neuro-Fuzzy and Applications CO5: Discuss applications computing to solve real life pro- 	ribe soft ir roles in 1 Neural tems and 7 Systems s of soft oblems
UNIT 1		CO1
Introduction: Introduction to soft computing; introduc artificial neural network, introduction to fuzzy sets and	ction to biological and I fuzzy logic systems.	4 Hrs
UNIT 2 Artificial Neural Networks and Applications: Diffe models, learning in artificial neural networks, neur control systems.	erent artificial neural network ral network applications in	CO2 5 Hrs
UNIT 3 <i>Fuzzy Systems and Applications:</i> Fuzzy seinference systems, fuzzy control, fuzzy clustering, app	ets; fuzzy reasoning, fuzzy lications of fuzzy systems.	CO3 l2Hrs

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UNIT 4 Neuro-Fuzzy Systems: Neuro-fuzzy modeling, Neuro-fuzzy control. Genetic Algorithms- Simple GA, crossover and mutation, genetic algorithms in search and optimization.	CO4 10 Hrs
UNIT 5	CO5 8Hrs
Applications: Pattern Recognitions, Image Processing, Biological Sequence Alignment and Drug Design, Robotics and Sensors, Information Retrieval Systems	
Share Market Analysis, Analysis language processing.	

Text Books:

S. No.	Title	Authors	Edition	Publisher
1	Fuzzy Logic And Soft Computing	Chen, Guoging, Ving, Mingsheng & Cai, Kai Yuan		Ed – Kluwar Academic
2	Soft Computing and Intelligent Systems Design Theory Tools and Applications	Karray F O & Desilva C	3rd Edition	Pearson, New Delhi

Reference Books:

S. No.	Title	Authors	Edition	Publisher
1	A Computational intelligence: principles, techniques, and applications	Konar	10th Edition	Springer
2	Neuro-fuzzy and soft computing: a computational approach to learning and machine intelligence	Jang, J S R, Sun, C T, & Mizutani E	2004	Prentice Hall

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disease.

Subject Code EEE100472	Introduction to Machine Learning	L = 3	T = 3	P = 0	Credits = 3
Fyaluation	ESE	СТ	ТА	Total	ESE Duration
Scheme	100	20	30	150	3 Hours

Course Objectives	Course Outcome	s
The objective of the course to:	On successful completion of	the course,
 To understand fundamental concepts of machine learning and its various algorithms. To understand various strategies of generating models from data and evaluating them. To apply ML algorithms on given data and interpret the results obtained Explore supervised/unsupervised machine learning algorithms for classification/prediction/clustering 	 the student will be able to: CO1: Develop a good understan of fundamental principles of mac learning. CO2: To compare and contrast and cons of various machine lear techniques. CO3: Evaluate performance various machine learning algorit on various data sets of a domain. 	
UNIT 1 Machine Learning- Machine Learning and its applic Machine Learning, Supervised Machine Learning ,Ur Learning, Supervised Vs Unsupervised Learning, Exa	ations, Life cycle of nsupervised Machine nmples of Machine Learning	CO1 10 Hrs
UNIT 2 Regression Analysis- Linear Regression, Simple I Linear Regression, Backward Elimination, Polyne Regression, Linear Regression Vs Logistic Regression	Linear Regression, Multiple omial Regression, Logistic n	CO1,CO2 10 Hrs
UNIT 3 Classification - Classification Algorithm, Classification Classification Algorithms- K-NN, Support Vector Ma Decision Tree, RandomForest	on Vs Regression, achine ,Naïve Bayes Classifier,	CO3 10Hrs

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UNIT 4 Clustering- Clustering in Machine Learning, Hierarchical Clustering in Machine Learning, K-Means Clustering Algorithm, Machine Learning Vs A.I Vs Data Science Vs Deep Learning	CO3 8 Hrs
UNIT 5	CO2, CO3
	9Hrs
Mathematics & Coding in Machine Learning - Semi-Supervised Learning,	
Precision and Recall in Machine Learning, Overfitting in Machine Learning, Types	
of Encoding Techniques, Feature Selection Techniques in Machine Learning.	
 Clustering- Clustering in Machine Learning, Hierarchical Clustering in Machine Learning, K-Means Clustering Algorithm, Machine Learning Vs A.I Vs Data Science Vs Deep Learning UNIT 5 Mathematics & Coding in Machine Learning - Semi-Supervised Learning, Precision and Recall in Machine Learning, Overfitting in Machine Learning, Types of Encoding Techniques , Feature Selection Techniques in Machine Learning. 	CO2, CO3 9Hrs

Text Books:

S. No.	Title	Authors	Publisher
1	Machine Learning	Tom.M.Mitchell	McGraw Hill International Edition
2	Introduction to Machine Learning	E. Alpaydin	PHI, 2005.
3.	Machine Learning for Absolute Beginners	Oliver Theobald	Scatterplot Press, 2017

ReferenceBooks:

S. No.	Title	Authors	Publisher
1	Hands-On Machine Learning with Scikit-Learn, Keras, and TensorFlow	Geron Aurelien	Shroff/O'Reilly;
2	Deep Learning	Ian Goodfellow, Yoshua Bengioand Aaron Courville	MIT Press

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